



2023 3RD INTERNATIONAL CONFERENCE ON INDUSTRIAL AUTOMATION,
ROBOTICS AND CONTROL ENGINEERING

Call for papers

Topics of interest include, but are not limited to:

Systems and control

- Fuzzy System and Fuzzy Control
- Software Cybernetics
- Game Theory
- AI-driven Automation
- Knowledge Automation
- Control Theory and Technology
- Control Systems and Applications

Robotic systems

- Industrial Robots
- Robot Clusters
- Cobots
- Service Robots
- Soft Robots
- Bionic Robots
- Space Robots

AI and applications

- Fuzzy System and Fuzzy Control
- Information Systems and System Security
- Cloud Computing and Computing Intelligence
- Data Science and Big Data Computing
- Fault Diagnosis and Fault-tolerant Control
- Sensor Networks and the Internet of Things
- Intelligent Manufacturing and Industrial Intelligence

Keynote Speakers

Prof. Jianrong Tan

Zhejiang University, China

Academician of Chinese Academy of Engineering

Prof. Tingwen Huang

Texas A&M University, Qatar

Fellow of TWAS, Fellow of IEEE and IAPR

Prof. Guangbin Huang

Nanyang Technological University, Singapore

IEEE Fellow

Prof. Christos G. Cassandras

Boston University, USA

Fellow of IEEE, IFAC

Assoc. Prof. Wei Pan

University of Manchester, UK

More speakers to be announced...

Registration

Student/Committee Regular Author

500 USD

550 USD

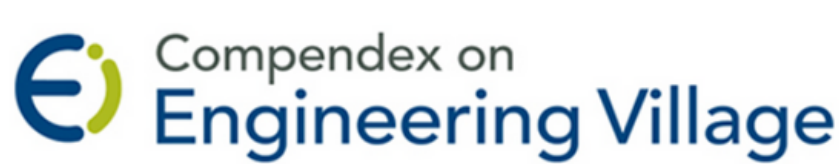
Key Dates

Full Submission: September 30, 2023

Registration: October 7, 2023

Publication Information

All accepted and presented papers of IARCE 2023 will be published in **IET Conference Proceedings**, which will be sent to be reviewed and indexed by major citation databases such as EI Compendex, etc.



Submission

<https://cmt3.research.microsoft.com/User/Login?ReturnUrl=%2FIARCE2023>



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 北京邮电大学  湖南科技大学

Co-organizers:  北京理工大学  华东理工大学



Committee

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Dan Yang

Southwest Jiaotong University, China

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Beihang University, China

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Yue Zhao

Chongqing University of Posts and Telecommunications, China

Award Chair

Hongjing Liang

University of Electronic Science and Technology of China, China